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Introduction, Part I: Differences between analogue and digital controllers (subtitles) 2/3/2014 Discrete Time Systems – Impulse Sampler \u0026amp; Zero Order Hold (Lecture 5 – Part I) Discrete Time Systems – Z transform \u0026amp; Zero Order Hold (Lecture 5 – Part II) State space feedback 7 – optimal control Response of a first order system to an impulse, 3/4/2014 State Space, Part 4: What is LQR control? [ECE320 Lecture10-1c: Discrete-Time Systems - Transfer Function Control](#) [Intro to Control - 5.1 Linearization Basics](#) An explanation of the Z transform part 1 State Variable Analysis in Discrete Time Domain – State Space Analysis – Control Systems **Discrete-Time-Systems - Pulse Transfer Functions of a Digital Control System (Lecture 6 - Part II)** *Digital control 10: Continuous-time models of discrete-time systems* Digital control 8: Stability of discrete-time systems *Digital control 9: Overview of discrete-time systems and signals*

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A comprehensive treatment of the analysis and design of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The book features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

Discrete-Time Control Systems: Ogata, Katsuhiko ...
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Notes for Discrete-Time Control Systems (ECE-520) Fall 2010 by R. Throne The major sources for these notes are † Modern Control Systems, by Brogan, Prentice-Hall, 1991. † Discrete-Time Control Systems, by Ogata. Prentice-Hall,

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1995. † Computer Controlled Systems, by "Åström and Wittenmark. Prentice-Hall, 1997.

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Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller (μP), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC). 3 + ? $r(t)$ $e(t)$ ADC μP DAC $u(t)$ Plant ? ? $y(t)$ 4

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